## 1 Bead on a Spinning Wire

This walks you through the problem.


A bead, with mass $m$, slides without friction on a long straight wire. The wire is spinning about one end at a constant angular speed $\omega$. Let $r$ be the position of the bead on the wire as measured from the point of rotation of the wire. There is no gravity. All the motion is in a plane.

### 1.1 Lagrangian

In terms of $r, \dot{r}, m, \omega$, and $t$, write an expression for the Lagrangian $L(r, \dot{r}, t)$ for this system. Note that $U=0$.

### 1.2 Lagrange's Equation of Motion

Using your Lagrangian, find the equation of motion for $r$.

### 1.3 Canonical Conjugate Momentum

In general, the canonical momentum that is conjugate (paired) to generalized position $q_{i}$ is $p_{q_{i}} \equiv p_{i}=\frac{\partial L}{\partial \dot{q}_{i}}$.
The canonical momentum that is conjugate to $r$ is $p_{r} \equiv \frac{\partial L}{\partial r}$. Find the canonical momentum that is conjugate to $r$ as a function of $r, \dot{r}, \omega$, and $t$.

### 1.4 Hamiltonian

The Hamiltonian in general can be defined as

$$
\begin{equation*}
H\left(q_{k}, p_{k}, t\right)=\sum_{j} p_{j} \dot{q}_{j}-L\left(q_{k}, \dot{q}_{k}, t\right), \tag{1.1}
\end{equation*}
$$

where the Hamiltonian must be written as a function of just the dependent dynamical variables $q_{k}, p_{k}$, and $t$. There must be no $\dot{q}_{k}$ dependence in $H$. So we are assuming that $\dot{q}_{k}$ can be written as a function of $q_{k}, p_{k}$, and $t$, in order to make this transformation.

In our case $H\left(r, p_{r}\right)=p_{r} \dot{r}-L(r, \dot{r})$. In terms of $r, p_{r}, m$, and $\omega$, find the Hamiltonian, $H\left(r, p_{r}, t\right)$ for this system.

### 1.5 Hamilton's Equations of Motion

In Lagrangian dynamics, for each generalized position, $q_{i},(i=1,2, \ldots s)$ there is an equation of motion that is a secondorder ordinary differential equation. In Hamiltonian Dynamics, for each corresponding second-order differential equation of Lagrangian dynamics there are two first-order ordinary differential equations, one of the generalized position, $q_{i}$, and one for the corresponding canonical momentum, $p_{q_{i}} \equiv p_{i}$. These Hamiltonian equations of motion are gotten from the Hamiltonian like so

$$
\begin{equation*}
\dot{q}_{i}=\frac{\partial H}{\partial p_{q_{i}}} \quad \text { and } \quad \dot{p}_{i}=-\frac{\partial H}{\partial q_{i}} \tag{1.2}
\end{equation*}
$$

Use the Hamiltonian that you just calculated and equations 1.2 to find the equations of motion for $r$ and $p_{r}$, and show that these equations of motion for $r$ and $p_{r}$ are equivalent to the equation of motion from section 1.2.

### 1.6 Energy vs Hamiltonian

In terms of $r, p_{r}, m, \omega$, and $t$, (a) find the difference between the total energy $E$ and the Hamiltonian $H$ for this system $(E-H)$. (b) Is $H$ constant in time? (c) Is $E$ constant in time? Note that $E=T=L$. Explain you results.

