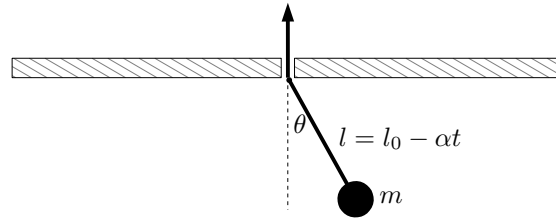


1 Shrinking Pendulum



A simple plane pendulum consists of a mass m attached to a massless string of length l . The suspension point of the pendulum remains fixed as the length, l , is shortened at a constant rate α , as shown above. The pendulum has a length l_0 at time $t = 0$. In this problem we'll find the equations of motion for the pendulum using the Lagrangian and the Hamiltonian method.

1.1 Lagrangian

In terms of θ , $\dot{\theta}$, m , α , l_0 , and t , write an expression for the Lagrangian, $L(\theta, \dot{\theta}, t)$, for this system.

1.1 solution

$$L = T - U = \frac{1}{2}m\dot{l}^2 + \frac{1}{2}ml^2\dot{\theta}^2 - mg(-l \cos \theta) \Rightarrow L(\theta, \dot{\theta}, t) = \frac{1}{2}m\alpha^2 + \frac{1}{2}m(l_0 - \alpha t)^2\dot{\theta}^2 + mg(l_0 - \alpha t) \cos \theta \quad (1.1)$$

1.2 Lagrange's Equations of Motion

Using your Lagrangian and Lagrange's equations, find the differential equation of motion for θ .

1.2 solution

$$\begin{aligned} \frac{\partial L}{\partial \theta} - \frac{dL}{dt} \frac{\partial L}{\partial \dot{\theta}} &= 0 \Rightarrow -mg(l_0 - \alpha t) \sin \theta - \frac{dL}{dt} [m(l_0 - \alpha t)^2 \dot{\theta}] = 0 \\ \Rightarrow -mg(l_0 - \alpha t) \sin \theta - 2m(l_0 - \alpha t)(-\alpha) \dot{\theta} - m(l_0 - \alpha t)^2 \ddot{\theta} &= 0. \end{aligned} \quad (1.2)$$

Dividing by $m(l_0 - \alpha t)$ and rearranging gives

$$\Rightarrow (l_0 - \alpha t) \ddot{\theta} = 2\alpha \dot{\theta} - g \sin \theta \quad (1.3)$$

1.3 Canonical Conjugate Momentum

Find the canonical momentum that is conjugate (paired) to θ . That is, find $p_\theta \equiv \frac{\partial L}{\partial \dot{\theta}}$, as a function of θ , $\dot{\theta}$, m , α , l_0 , and t .

1.3 solution

$$p_\theta = \frac{\partial L}{\partial \dot{\theta}} = m(l_0 - \alpha t)^2 \dot{\theta} \Rightarrow \boxed{p_\theta = m(l_0 - \alpha t)^2 \dot{\theta}} \quad (1.4)$$

1.4 Hamiltonian

In terms of θ , p_θ , m , α , l_0 , and t , write the Hamiltonian, $H(\theta, p_\theta, t)$ for this system.

1.4 solution

$$H = p_\theta \dot{\theta} - L = \left[m(l_0 - \alpha t)^2 \dot{\theta} \right] \dot{\theta} - \left[\frac{1}{2} m \alpha^2 + \frac{1}{2} m(l_0 - \alpha t)^2 \dot{\theta}^2 + mg(l_0 - \alpha t) \cos \theta \right]$$

$$= \frac{1}{2} m(l_0 - \alpha t)^2 \dot{\theta}^2 - \frac{1}{2} m \alpha^2 - mg(l_0 - \alpha t) \cos \theta \Rightarrow \boxed{H = \frac{p_\theta^2}{2m(l_0 - \alpha t)^2} - \frac{1}{2} m \alpha^2 - mg(l_0 - \alpha t) \cos \theta} \quad (1.5)$$

1.5 Hamilton's Equations of Motion

Find the Hamilton's equations of motion for θ and p_θ , and show that these equations of motion for θ and p_θ are equivalent to the equations of motion from subsection 1.2.

1.5 solution

$$\dot{p}_\theta = -\frac{\partial H}{\partial \theta} = -mg(l_0 - \alpha t) \sin \theta \Rightarrow \boxed{\dot{p}_\theta = -mg(l_0 - \alpha t) \sin \theta} \quad (1.6)$$

$$\dot{\theta} = \frac{\partial H}{\partial p_\theta} = \frac{p_\theta}{m(l_0 - \alpha t)^2} \Rightarrow \boxed{\dot{\theta} = \frac{p_\theta}{m(l_0 - \alpha t)^2}} \quad (1.7)$$

$$\Rightarrow \ddot{\theta} = \frac{\dot{p}_\theta}{m(l_0 - \alpha t)^2} - \alpha \frac{-2p_\theta}{m(l_0 - \alpha t)^3} = \frac{-mg(l_0 - \alpha t) \sin \theta}{m(l_0 - \alpha t)^2} + \alpha \frac{2m(l_0 - \alpha t)^2 \dot{\theta}}{m(l_0 - \alpha t)^3}$$

$$\Rightarrow (l_0 - \alpha t) \ddot{\theta} = 2\alpha \dot{\theta} - g \sin \theta, \quad (1.8)$$

which is the same as equation 1.3 from subsection 1.2.

1.6 Energy vs Hamiltonian

In terms of m , α , l_0 , and t , find the difference between the total energy, $T + U$, and the Hamiltonian for this system.

1.6 solution

$$E - H = \frac{p_\theta^2}{2m(l_0 - \alpha t)^2} + \frac{1}{2}m\alpha^2 - mg(l_0 - \alpha t)\cos\theta - \left[\frac{p_\theta^2}{2m(l_0 - \alpha t)^2} - \frac{1}{2}m\alpha^2 - mg(l_0 - \alpha t)\cos\theta \right]$$
$$\Rightarrow \boxed{E - H = m\alpha^2} \quad (1.9)$$

So E and H only differ by a constant.

