

1 Uniform Gravitational Field

The idea of changing dynamical variables in order to split a Lagrangian into independent pieces can be applied to systems with noncentral-forces too.

Consider two particles, one with mass m_1 and position given by \vec{r}_1 , and the other with mass m_2 and position given by \vec{r}_2 , with both subject to a uniform constant gravitational field \vec{g} and interacting with each other with potential energy $U_r(|\vec{r}_1 - \vec{r}_2|)$. **(a)** Write the Lagrangian for this system using coordinates \vec{r}_1 and \vec{r}_2 , $L(\vec{r}_1, \vec{r}_2, \dot{\vec{r}}_1, \dot{\vec{r}}_2)$. **(b)** Make the change of variables from \vec{r}_1, \vec{r}_2 to \vec{r}, \vec{R} , where

$$\vec{r} = \vec{r}_1 - \vec{r}_2, \quad \vec{R} = \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2}{m_1 + m_2}, \quad (1.1)$$

and show that the transformed Lagrangian can be split into two parts like so

$$L = L_{\text{cm}}(\vec{R}, \dot{\vec{R}}) + L_{\mu}(\vec{r}, \dot{\vec{r}}). \quad (1.2)$$

Identify L_{cm} and L_{μ} . You may want to define, μ , the reduced mass as

$$\mu = \frac{m_1 m_2}{m_1 + m_2}. \quad (1.3)$$

(c) Using equation 1.2, explain how the dynamics of \vec{R} and \vec{r} are independent of each other.

1.0 solution

$$L = T - U = \frac{1}{2} m_1 (\dot{\vec{r}}_1)^2 + \frac{1}{2} m_2 (\dot{\vec{r}}_2)^2 - U_r(|\vec{r}_1 - \vec{r}_2|) - (-m_1 \vec{g} \cdot \vec{r}_1) - (-m_2 \vec{g} \cdot \vec{r}_2)$$

$$\Rightarrow \quad \text{(a)} \quad L(\vec{r}_1, \vec{r}_2, \dot{\vec{r}}_1, \dot{\vec{r}}_2) = \frac{1}{2} m_1 (\dot{\vec{r}}_1)^2 + \frac{1}{2} m_2 (\dot{\vec{r}}_2)^2 - U_r(|\vec{r}_1 - \vec{r}_2|) + m_1 \vec{g} \cdot \vec{r}_1 + m_2 \vec{g} \cdot \vec{r}_2 \quad (1.4)$$

From inverting equations 1.1 and differentiating with respect to time we have

$$\vec{r}_1 = \vec{R} + \frac{m_2}{m_1 + m_2} \vec{r}, \quad \vec{r}_2 = \vec{R} - \frac{m_1}{m_1 + m_2} \vec{r}, \quad \dot{\vec{r}}_1 = \dot{\vec{R}} + \frac{m_2}{m_1 + m_2} \dot{\vec{r}}, \quad \text{and} \quad \dot{\vec{r}}_2 = \dot{\vec{R}} - \frac{m_1}{m_1 + m_2} \dot{\vec{r}}. \quad (1.5)$$

Replacing \vec{r}_1, \vec{r}_2 with \vec{R}, \vec{r} in the Lagrangian L gives

$$L = \frac{1}{2} m_1 \left(\dot{\vec{R}} + \frac{m_2}{m_1 + m_2} \dot{\vec{r}} \right)^2 + \frac{1}{2} m_2 \left(\dot{\vec{R}} - \frac{m_1}{m_1 + m_2} \dot{\vec{r}} \right)^2 - U_r(|\vec{r}|) + m_1 \vec{g} \cdot \left(\vec{R} + \frac{m_2}{m_1 + m_2} \vec{r} \right) + m_2 \vec{g} \cdot \left(\vec{R} - \frac{m_1}{m_1 + m_2} \vec{r} \right)$$

$$= \frac{1}{2} m_1 (\dot{\vec{R}})^2 + \frac{1}{2} \frac{m_1 m_2^2}{(m_1 + m_2)^2} (\dot{\vec{r}})^2 + \frac{m_1 m_2}{m_1 + m_2} (\dot{\vec{R}} \cdot \dot{\vec{r}}) +$$

$$\frac{1}{2} m_2 (\dot{\vec{R}})^2 + \frac{1}{2} \frac{m_1^2 m_2}{(m_1 + m_2)^2} (\dot{\vec{r}})^2 - \frac{m_1 m_2}{m_1 + m_2} (\dot{\vec{R}} \cdot \dot{\vec{r}}) -$$

$$U_r(|\vec{r}|) + m_1 \vec{g} \cdot \vec{R} + m_2 \vec{g} \cdot \vec{R} + \frac{m_1 m_2}{m_1 + m_2} \vec{g} \cdot \vec{r} - \frac{m_1 m_2}{m_1 + m_2} \vec{g} \cdot \vec{r}$$

$$= \frac{1}{2} (m_1 + m_2) (\dot{\vec{R}})^2 + \frac{1}{2} \frac{m_1 m_2^2 + m_1^2 m_2}{(m_1 + m_2)^2} (\dot{\vec{r}})^2 - U_r(|\vec{r}|) + (m_1 + m_2) \vec{g} \cdot \vec{R}. \quad (1.6)$$

Digression:

$$\frac{1}{2} \frac{m_1 m_2^2 + m_1^2 m_2}{(m_1 + m_2)^2} (\dot{\vec{r}})^2 = \frac{1}{2} \frac{(m_1 + m_2) m_1 m_2}{(m_1 + m_2)^2} (\dot{\vec{r}})^2 = \frac{1}{2} \frac{m_1 m_2}{m_1 + m_2} (\dot{\vec{r}})^2 = \frac{1}{2} \mu (\dot{\vec{r}})^2, \quad (1.7)$$

where

$$\mu \equiv \frac{m_1 m_2}{m_1 + m_2}.$$

So equation 1.6 becomes

$$\begin{aligned} L &= \frac{1}{2} (m_1 + m_2) (\dot{\vec{R}})^2 + \frac{1}{2} \mu (\dot{\vec{r}})^2 - U_r(|\vec{r}|) + (m_1 + m_2) \vec{g} \cdot \vec{R} \\ &= \left[\frac{1}{2} (m_1 + m_2) (\dot{\vec{R}})^2 + (m_1 + m_2) \vec{g} \cdot \vec{R} \right] + \left[\frac{1}{2} \mu (\dot{\vec{r}})^2 - U_r(|\vec{r}|) \right]. \end{aligned} \quad (1.8)$$

So if

$$L = L_{\text{cm}}(\vec{R}, \dot{\vec{R}}) + L_{\mu}(\vec{r}, \dot{\vec{r}}), \quad (1.9)$$

then

$$L_{\text{cm}}(\vec{R}, \dot{\vec{R}}) = \frac{1}{2} (m_1 + m_2) (\dot{\vec{R}})^2 + (m_1 + m_2) \vec{g} \cdot \vec{R}$$

and

$$L_{\mu}(\vec{r}, \dot{\vec{r}}) = \frac{1}{2} \mu (\dot{\vec{r}})^2 - U_r(|\vec{r}|) \quad (1.10)$$

(c) This is pretty obvious, but there goes. We can write Lagrange's equation for a given generalized coordinate q_i and a Lagrangian $L = L_1 + L_2$ as

$$\frac{\partial}{\partial q_i} (L_1 + L_2) + \frac{d}{dt} \frac{\partial}{\partial \dot{q}_i} (L_1 + L_2) = 0. \quad (1.11)$$

So if L_2 does not depend on q_i or \dot{q}_i then equation 1.11 becomes

$$\frac{\partial}{\partial q_i} L_1 + \frac{d}{dt} \frac{\partial}{\partial \dot{q}_i} L_1 = 0, \quad (1.12)$$

and so L_2 does not have any effect on the dynamics of q_i . So in general the the dynamics of variables in a Lagrangian are not effected by terms in the Lagrangian that do not contain the variable. So in general if terms in a Lagrangian are independent of other terms in a the Lagrangian, and visa versa, then you have dynamical systems that are independent of each other. In our case the dynamics of \vec{r} is independent of \vec{R} and visa versa.

2 Orbit of a Free Particle

It was shown in your text, Thornton and Marion (equation 8.21), that the orbital path $r(\theta)$ can be found from the ordinary differential equation

$$\frac{d^2}{d\theta^2} \left(\frac{1}{r} \right) + \frac{1}{r} = -\frac{\mu r^2}{l^2} F(r), \quad (2.1)$$

where l is the constant angular momentum, $\mu = \frac{m_1 m_2}{m_1 + m_2}$ is the reduced mass of the two particles, and $F(r)$ is the force. Find the orbital path, $r(\theta)$, when there is no force, $F(r) = 0$. What is the common name of the curve of this orbital path?

2.0 solution

$$\frac{d^2}{d\theta^2} \left(\frac{1}{r} \right) + \frac{1}{r} = 0 \quad \Rightarrow \quad \boxed{\frac{1}{r} = C_1 \cos \theta + C_2 \sin \theta}. \quad (2.2)$$

To more easily see what this polar plot, $r(\theta)$, is, we can look at it in Cartesian coordinates where $x = r \cos \theta$, and $y = r \sin \theta$. Writing equation 2.3 in terms of x , y , and r gives

$$\frac{1}{r} = C_1 \frac{x}{r} + C_2 \frac{y}{r} \quad \Rightarrow \quad \boxed{1 = C_1 x + C_2 y}, \quad (2.3)$$

which is easy to identify as the equation of a straight line, as expected.

3 Find a Force from an Orbit

Find the central force, $F(r)$, that allows a particle to move in a spiral orbit given by $r = k\theta^2$, where k is a constant.

3.0 solution

From equation 2.1

$$F(r) = -\frac{l^2}{\mu r^2} \frac{d^2}{d\theta^2} \left(\frac{1}{r} \right) - \frac{l^2}{\mu r^2} \frac{1}{r} = -\frac{l^2}{\mu r^2} \frac{d}{d\theta} \left(-2 \frac{1}{k\theta^3} \right) - \frac{l^2}{\mu r^2} \frac{1}{k\theta^2} \quad (3.1)$$

$$= -\frac{l^2}{\mu r^2} \left(6 \frac{1}{k\theta^4} \right) - \frac{l^2}{\mu r^2} \frac{1}{k\theta^2} = -\frac{l^2}{\mu r^2} \left(6 \frac{1}{k \left(\frac{r}{k} \right)^2} \right) - \frac{l^2}{\mu r^2} \frac{1}{k \frac{r}{k}} \quad (3.2)$$

$$\Rightarrow \quad \boxed{F(r) = -\frac{l^2}{\mu} \left(\frac{6k}{r^4} + \frac{1}{r^3} \right)}. \quad (3.3)$$

4 Time to Collide

Two particles are attracted to each other by gravity. They are in circular orbits about each other. The period of the orbital motion is τ . If the two particles are suddenly stopped in their orbits and allowed to be pulled straight toward each other by their gravitational attraction, show that they will collide after a time of $\frac{\tau}{4\sqrt{2}}$.

4.0 solution

For a circular orbit in polar coordinates (r, θ) $r = \text{const} = b$, and so is $\dot{\theta}$. We define $\dot{\theta} \equiv \omega$. Balancing force and centripetal acceleration for both particles as there go around the center of mass gives

$$m_1 r_1 \omega^2 = G \frac{m_1 m_2}{b^2} \quad \Rightarrow \quad r_1 = G \frac{m_2}{\omega^2 b^2}, \quad (4.1)$$

and

$$m_2 (b - r_1) \omega^2 = G \frac{m_1 m_2}{b^2} \quad \Rightarrow \quad b - r_1 = G \frac{m_1}{\omega^2 b^2}, \quad (4.2)$$

where m_1 and m_2 are the masses of the two particles, b is the distance between the two particles, and r_1 is the distance from the center of mass to particle 1. Adding equations 4.1 and 4.2 gives

$$b = \frac{G}{\omega^2 b^2} (m_1 + m_2) \Rightarrow b = \frac{Gm_1m_2}{\mu\omega^2 b^2} \Rightarrow b^3 = \frac{Gm_1m_2}{\mu\omega^2} = \frac{Gm_1m_2\tau^2}{4\pi^2\mu}, \quad (4.3)$$

where we used $\omega\tau = 2\pi$ in the last step. We release the two particles from rest at a distance of b apart. The equation of motion for r can be written using conservation of energy with the initial r value of b giving

$$U_i + T_i = U_f + T_f \Rightarrow -\frac{Gm_1m_2}{b} = -\frac{Gm_1m_2}{r} + \frac{1}{2}\mu\dot{r}^2 \Rightarrow dt = -\frac{\mu}{\sqrt{2Gm_1m_2}} \frac{dr}{\sqrt{\frac{1}{r} - \frac{1}{b}}},$$

where we picked the minus sign since $\frac{dr}{dt}$ is less than zero when the particles move toward each other. Setting t to the time for colliding gives

$$\Rightarrow t = -\frac{\mu}{\sqrt{2Gm_1m_2}} \int_{r=b}^0 \frac{dr}{\sqrt{\frac{1}{r} - \frac{1}{b}}} = -\frac{\mu}{\sqrt{2Gm_1m_2}} \int_{r=b}^0 \frac{dr}{\sqrt{\frac{b-r}{br}}} = \frac{\mu\sqrt{b}}{\sqrt{2Gm_1m_2}} \int_{r=0}^b \frac{\sqrt{r} dr}{\sqrt{b-r}}. \quad (4.4)$$

With the change of variables $x^2 = r/b$, $2bx dx = dr$

$$t = \frac{\mu\sqrt{b}}{\sqrt{2Gm_1m_2}} \int_{x=0}^1 \frac{\sqrt{ax^2} 2bx dx}{\sqrt{b-bx^2}} = \frac{\mu b\sqrt{2b}}{\sqrt{Gm_1m_2}} \int_{x=0}^1 \frac{x^2 dx}{\sqrt{1-x^2}}. \quad (4.5)$$

For the integral we have

$$\int_{x=0}^1 \frac{x^2 dx}{\sqrt{1-x^2}} = \left(-\frac{x}{2}\sqrt{1-x^2} + \frac{1}{2}\sin^{-1} x \right) \Big|_{x=0}^1 = \frac{\pi}{4}.$$

Combining this with equation 4.5 and 4.3 gives

$$t = \frac{\mu\sqrt{2b}^{\frac{3}{2}}}{\sqrt{Gm_1m_2}} \frac{\pi}{4} = \frac{\sqrt{2}\mu\sqrt{\frac{Gm_1m_2\tau^2}{4\pi^2\mu}}}{\sqrt{Gm_1m_2}} \frac{\pi}{4} \Rightarrow \boxed{t = \frac{\tau}{4\sqrt{2}}}. \quad (4.6)$$

