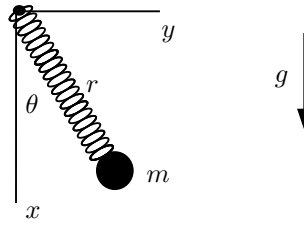


1 Springy Pendulum



The springy pendulum shown above has a rest spring length a , a spring constant k , and a bob mass of m . r is the distance from the origin (pivot point) to the bob. Find **(a)** the Lagrangian, $L(r, \theta, \dot{r}, \dot{\theta})$, and **(b)** the differential equations of motion. Simplify your results.

1.0 solution

$$L = T - U = \frac{1}{2}m\dot{r}^2 + \frac{1}{2}mr^2\dot{\theta}^2 - \frac{1}{2}k(r - a)^2 - mg(-x)$$

$$\Rightarrow \text{(a)} \quad \boxed{L(r, \theta, \dot{r}, \dot{\theta}) = \frac{1}{2}m\dot{r}^2 + \frac{1}{2}mr^2\dot{\theta}^2 - \frac{1}{2}k(r - a)^2 + mgr \cos \theta} \quad (1.1)$$

$$\frac{\partial L}{\partial r} - \frac{d}{dt} \frac{\partial L}{\partial \dot{r}} = 0 \quad \Rightarrow \quad mr\dot{\theta}^2 - k(r - a) + mg \cos \theta - \frac{d}{dt}(m\dot{r}) = 0$$

$$\Rightarrow \text{(b)} \quad \boxed{m\ddot{r} = -k(r - a) + mr\dot{\theta}^2 + mg \cos \theta} \quad (1.2)$$

$$\frac{\partial L}{\partial \theta} - \frac{d}{dt} \frac{\partial L}{\partial \dot{\theta}} = 0 \quad \Rightarrow \quad -mgr \sin \theta - \frac{d}{dt}(mr^2\dot{\theta}) = 0 \quad \Rightarrow \quad -mgr \sin \theta - (mr^2\ddot{\theta} + 2mr\dot{r}\dot{\theta}) = 0$$

$$\Rightarrow \text{(b)} \quad \boxed{r\ddot{\theta} = -g \sin \theta - 2\dot{r}\dot{\theta}} \quad (1.3)$$